



XYZ3TM+ STACKED SYSTEM

ASME-NGNN-08-0365-0355xx

VULCAN02 XYZ3TM+ with AccurET VHP

Data sheet

Version 1.1

ETEL

AXIS DESIGNATION						
Number of controlled axes	8					
Axes name	X1-X2	Y (top axis)	Fine Z	Tip-Tilt	Theta	Coarse Z
Thrust transmitter: DD (direct drive) or ID (indirect drive)	DD	DD	DD	DD	DD	DD

TESTING CONDITIONS		UNIT				
Position controller	-		VHP 100 10/30A	VHP 100 10/30A	VHP48	VHP100
Motion controller	-		ULTIMET ADVANCED			
Rated payload (1)	kg		2			
Rated inertia (1)	kg.m ²		-	-	-	0.018
Rated input voltage	VDC		96	96	48	96
Tool point position	mm		324 mm above bottom surface			
Ambient temperature	°C		22 ± 1			
Isolation system	-		QuiET			

DIMENSIONAL DATA		UNIT				
Width	mm		779			
Length	mm		802			
Height	mm		304			
Total stroke	mm or °		365	355	±2	±0.08
Moving mass (without payload)	kg		39.3	17.3	5	0.6
Total mass (without payload)	kg		165			
Rotor inertia (without payload)	kg.m ²		NA	NA	NA	0.004

FORCE / TORQUE CAPABILITIES		UNIT				
Peak force / torque	N or Nm		1970	594	65.3	7.36
Continuous force / torque	N or Nm		458	162	15.7	0.831
Standstill force / torque	N or Nm		346	122	-	0.669
Max. detent force / torque (average to peak)	N or Nm		34	12	-	0
Static friction (maximal value)	N or Nm		10.7	11.8	-	0.2
Dynamic friction (maximal value)	N/(m/s) or Nm/(rad/s)		23.5	28.7	-	0.2

LOAD CAPACITIES		UNIT				
Maximum axial load	N		-	-	-	25

DYNAMIC PERFORMANCE		UNIT				
Duty cycle	%		20		-	6
Maximum speed	m/s or rad/s		1	1.2	0.1	10
Maximum acceleration	m/s ² or rad/s ²		25	25	3	180
Typical position stability at 2 kHz	nm or arcsec		±2	±2	±3	±0.025

ENCODER CHARACTERISTICS		UNIT				
Encoder and signal type	-		Optical incremental	Optical incremental	Optical Incremental	Optical incremental
Output signal	-		1 Vpp	1 Vpp	1 Vpp	EnDat 2.2
Signal period or line count	µm or period/turn		4	4	4	18'000
Reference mark	-		One	One	One centered in Z	One
Power supply	V		5	5	5	5

WORKING ENVIRONMENT		UNIT				
Clean room compatibility (2)	-		ISO2			

GUIDING ELEMENTS		UNIT				
Type	-		Ball bearing	Ball bearing	Flexures	Ball bearing

OPTIONS / ACCESSORIES / FEATURES		UNIT				
Gravity compensation	N		N/A	N/A	Yes	Yes

ACCURACY	UNIT	X1-X2	Y (top axis)	Fine Z	Tip-Tilt	Theta	Coarse Z
Positioning accuracy (without mapping)	µm or arcsec	±10	±30	-	-	±30	-
Positioning accuracy (with mapping)	µm or arcsec	±1	±1	-	-	-	-
Unidirectional repeatability	µm or arcsec	-	-	-	-	-	±10 (4) / ±5 (5)
Bidirectional repeatability	µm or arcsec	±0.4 (3)	±0.4 (3)	±0.03	-	±2	±15 (4) / ±7.5 (5)
Horizontal straightness / radial runout	µm	±1.5	±3.5	-	-	±3.5	-
Vertical straightness / total axial error at 0 [mm] radius	µm	±3	±5	-	-	±3	-
XY displacement while moving in Z (6)	µm	N/A	N/A	±0.1	-	-	±15
Orthogonality	arcsec	±15	-	-	-	-	-
Rx (with mapping)	arcsec	±20	±25	-	±20	-	-
Ry (with mapping)	arcsec	±20	±60	-	±20	-	-
Rz	arcsec	±1.5	±10	-	-	-	-

ELECTRICAL SPECIFICATIONS (7)	UNIT	Ironcore	Ironcore	Electro-Magnet	Ironless	Electro-Magnet
Motor type	-	LMG10-070-3SB-H01	LMG10-050-3TB-209	EMF-14.5-058-1NA-219	SLICE0109-15	EMG012-075
Motor model	-					
Number of phases	-	3	3	3 x single-phase	3	1
Kt Force constant	N/Arms or Nm/Arms	41.7	23.4	19.6	0.646	10.7
Ku Back EMF constant (8)	Vrms/(m/s) or Vrms/(rad/s)	25.2	14.2	19.6	0.372	10.9
Km Motor constant	N/√W or Nm/√W	30.4	24.6	8.34	0.309	6.11
R20 Electrical resistance at 20°C (8)	Ohm	1.25	0.605	5.5	2.92	3.06
L1 Electrical inductance (8)	mH	8.89	3.77	13.5	5.52	8.97
Ip Peak current	Arms	46.5	30	3.38	11.8	3.49
Ic Continuous current	Arms	5.69	7.22	0.8	1.33	1.05
Is Standstill current	Arms	4.32	5.47	-	1.01	-
ns Standstill speed	m/s or rad/s	0.14	0.14	-	-	-
Um Max. input voltage	VDC	100	100	48	100	100
Pc Max. cont. power dissipation	W	76.9	62.5	3.88	8.75	3.93
2τp Magnetic period	mm	32	32	-	-	-
2p Number of poles	-	-	-	-	32	-

VACUUM CHARACTERISTICS	UNIT						
Vacuum supply for wafer chuck	bar	-0.6					
Vacuum flow for axis cleanliness	l/min	20	20	-	-	5	5

TYPICAL MOVE AND SETTLE TIMES	UNIT						
Move 1: 10 µm within ±100 nm window	ms	40	40	-	-	-	-
Move 2: 25 mm within ±100 nm window	ms	125	125	-	-	-	-
Move 3: 80 mm within ±100 nm window	ms	170	185	-	-	-	-
Move 4: 100 µm within ±50 nm window	ms	-	-	60	-	-	-
Move 5: 1 mm within ±50 nm window	ms	-	-	100	-	-	-
Move 6: 10 mm within ±500 nm window	ms	-	-	-	-	-	180
Move 7: 1 deg within ±40 µdeg window	ms	-	-	-	-	70	-
Move 8: 180 deg within ±40 µdeg window	ms	-	-	-	-	450	-

MATERIAL AND FINISH						
Baseplate	-	Granite	Aluminium & silicon alloy	Anodized aluminum	-	Stainless steel
Carriage	-	Aluminium & silicon alloy	Stainless steel	Anodized aluminum	Stainless steel	Stainless steel

According to the Machinery Directive 2006/42/EC, the system presently described falls into the "partly completed machinery" category and fully complies with it as long as the system is operated according to the working conditions described in the corresponding manual. Customer is responsible for setting safeties/limitations that will keep the motor in its safe operating area. ETEL cannot be held responsible if the system is used in an improper way.

Notes: The specifications given may be mutually exclusive. Unless stated otherwise, all measurements are made within the testing conditions.

- (1) Payload can be assimilated to a cylinder of diameter 270 mm, 19 mm thick, weighting 2 kg. Inertia is expressed with respect to the center of gravity of the payload, Z being the axis of rotation.
- (2) Under horizontal laminar flow conditions at 0.45 m/s along X axis. Measured at 12 mm above customer mobile interface. Contact ETEL for more details.
- (3) Acceleration used is 20 m/s²
- (4) Measured at a radius of 150 mm over full stroke.
- (5) Measured at a radius of 150 mm over a limited stroke of 0 to +3 mm.
- (6) Maximum displacement measured on a 100 µm sliding window, wherever the position on the fine Z stroke.
- (7) Tolerances on electrical parameters are available upon request.
- (8) Terminal to terminal.